WISB333 2022 Examination Problems

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1 Hopf bifurcation in ZH normal form

Consider the planar system

$$\begin{cases} \dot{\xi} = \beta_1 + \xi^2 + \rho^2, \\ \dot{\rho} = \rho(\beta_2 + \theta\xi + \xi^2), \end{cases}$$
(1.1)

where $\theta < 0$. This system appears in the analysis of the fold-Hopf codim 2 bifurcation of equilibria as an amplitude system for the truncated normal form, so that $\rho \ge 0$.

- 1. Find parameter values at which bifurcations of equilibria with $\rho = 0$ occur.
- 2. Verify that Hopf bifurcation of an equilibrium with small $\rho > 0$ happens in the system (1.1) at the line

$$T = \{ (\beta_1, \beta_2) : \beta_2 = 0, \ \beta_1 < 0 \}.$$

Derive an expression for the first Lyapunov coefficient l_1 along the Hopf line T and predict stability of the bifurcating cycle.

- 3. Illustrate your predictions by simulations with pplane and by numerical continuation in MatCont.
- 4. Try to obtain as complete as possible bifurcation diagram of (1.1) near the origin for small $\|\beta\|$.

2 Hopf bifurcation in R2 normal form

Consider the planar system

$$\begin{cases} \dot{\zeta}_1 = \zeta_2, \\ \dot{\zeta}_2 = \beta_1 \zeta_1 + \beta_2 \zeta_2 - \zeta_1^3 - \zeta_1^2 \zeta_2. \end{cases}$$
(2.1)

This system appears in the study of codim 2 bifurcation of limit cycles corresponding to a double multiplier -1.

1. Verify that Hopf bifurcation of the trivial equilibrium $(\zeta_1, \zeta_2) = (0, 0)$ of (2.1) happens at the line

$$H^{(1)} = \{ (\beta_1, \beta_2) : \beta_2 = 0, \ \beta_1 < 0 \},\$$

2. Verify that Hopf bifurcation of the nontrivial equilibria $(\zeta_1, \zeta_2) \neq (0, 0)$ of (2.1) happens at the line

$$H^{(2)} = \{ (\beta_1, \beta_2) : \beta_1 = \beta_2, \ \beta_1 > 0 \},\$$

- 3. Compute symbolically the first Lyapunov coefficient l_1 along the lines $H^{(1)}$ and $H^{(2)}$ and predict stability of the bifurcating cycles.
- 4. Verify your results by simulations with pplane and by numerical continuation in MatCont.
- 5. Try to obtain as complete as possible bifurcation diagram of (2.1) near the origin for small $\|\beta\|$.

3 Hopf bifurcation in Selkov's model

Consider the following simplifyed model of glycolysis

$$\begin{cases} \dot{x} = -x + ay + x^2 y, \\ \dot{y} = b - ay - x^2 y \end{cases}$$
(3.1)

where x is the concentration ADP (adenosine diphosphate) and y is the concentration F6P (fructose-6-phosphate). The parameters a, b affect the speed of the reaction from F6P to ADP and the addition of F6P, respectively.

- 1. Show that the triangle in the positive quadrant bounded by $y + x \leq C$ contains a trapping region for some constant C. Pay attention to the points (x, y) = (b, b/a) and the point where the triangle hits the x-nullcline.
- 2. Determine a curve a(b) on which the equilibrium exhibits a Hopf bifurcation and compute the first Lyapunov coefficient.
- 3. Use Poincaré-Bendixson to classify solutions of the system.
- 4. Illustrate your predictions by simulations in pplane.

4 Hopf bifurcation in the advertising model by Feichtinger

Consider the following planar system

$$\begin{cases} \dot{x}_1 = \alpha [1 - x_1 x_2^2 + A(x_2 - 1)], \\ \dot{x}_2 = x_1 x_2^2 - x_2, \end{cases}$$
(4.1)

where A > 0 is constant and α is a bifurcation parameter.

- 1. Check that the system (4.1) has an equilibrium that exhibits a Hopf bifurcation at some value $\alpha_{\rm H} = \alpha_{\rm H}(A)$ of parameter α . Verify also that the eigenvalues cross the imaginary axis at nonzero velocity w.r.t. the parameter.
- 2. Compute the corresponding first Lyapunov coefficient l_1 symbolically.
- 3. Confirm your results by simulations with pplane or by numerical continuation of the limit cycle in MatCont.

5 Adaptive control - I

Consider the following system from Control Theory

$$\begin{cases} \dot{x} = 1 + x - xy, \\ \dot{y} = \alpha y + \beta x^2, \end{cases}$$
(5.1)

where (α, β) are parameters. Assume that $\alpha < 0$.

- (a) Find fold and Hopf bifurcation curves of (5.1) in the parameter halfplane $\alpha < 0$.
- (b) Verify that (5.1) exhibits a Bogdanov-Takens (BT) bifurcation at $(\alpha, \beta) = (-\frac{2}{3}, \frac{8}{81})$, i.e., has an equilibrium with a double zero eigenvalue. (*Hint*: This is a common point with $\alpha < 0$ of the fold and Hopf bifurcation curves.)
- (c) Compute the coefficients (a, b) of the critical BT normal form and prove that the corresponding bifurcation is nondegenerate, i.e.,

$$ab \neq 0.$$

- (d) Fix $\alpha = -0.25$ and produce with pplane the phase portraits for $\beta = 0.05, 0.03, 0.01$, and 0.003.
- (e) Sketch the bifurcation diagram of (5.1). Where do you put the homoclinic bifurcation curve?
- (f) Indicate the region where the system has a stable equilibrium.

6 Averaged forced Van der Pol oscillator

Consider the following planar system studied by Holmes and Rand:

$$\begin{cases} \dot{x} = -\omega y + x(1 - x^2 - y^2), \\ \dot{y} = \omega x + y(1 - x^2 - y^2) - F, \end{cases}$$
(6.1)

where (ω, F) are positive parameters.

- (a) Find fold and Hopf bifurcation curves of (6.1) in the first quadrant of the parameter plane, i.e. when $\omega, F > 0$. (*Hint*: In both cases, express F as functions of ω .)
- (b) Verify that two branches of the fold curve in (6.1) meet at a cusp point (CP) with

$$\omega = \left(\frac{1}{3}\right)^{1/2}, \ F = \left(\frac{2}{3}\right)^{3/2}$$

(c) Verify that (6.1) exhibits a Bogdanov-Takens (BT) bifurcation at

$$\omega = F = \frac{1}{2},$$

i.e., has an equilibrium with a double zero eigenvalue.

(d) Compute the coefficients (a, b) of the critical BT normal form and prove that the corresponding bifurcation is nondegenerate, i.e.,

$$ab \neq 0.$$

- (e) Sketch the bifurcation diagram of (6.1). Where do you put the homoclinic bifurcation curve?
- (f) Verify your results by simulations with pplane and by numerical continuation in MatCont.

7 Prey-predator dynamics - I

Consider the following prey-predator model depending on two positive parameters (α,δ)

$$\begin{cases} \dot{x} = x - \frac{xy}{1 + \alpha x}, \\ \dot{y} = -y - \delta y^2 + \frac{xy}{1 + \alpha x}, \end{cases}$$
(7.1)

for $x, y \ge 0$.

1. Derive equations for the saddle-node and Hopf bifurcations of positive equilibria in the system. *Hint*: Consider the orbitally-equivalent to (7.1) polynomial system

$$\begin{cases} \dot{x} = x(1 + \alpha x) - xy, \\ \dot{y} = -(y + \delta y^2)(1 + \alpha x) + xy. \end{cases}$$
(7.2)

- 2. Prove that a Bogdanov-Takens bifurcation occurs in the system (7.2) and find the corresponding parameter values.
- 3. Compute the coefficients a and b of the BT-normal form.
- 4. Use pplane and MatCont to produce representative phase portraits of the model and to sketch its simplest possible bifurcation diagram.

8 Prey-predator dynamics - II

Consider the following prey-predator model depending on two parameters (l, m)

$$\begin{cases} \dot{x} = x(x-l)(1-x) - xy, \\ \dot{y} = -y(m-x), \end{cases}$$
(8.1)

where m > 0 and 0 < l < 1, and $x, y \ge 0$.

- 1. Derive equations for the borders of a domain in the (l, m)-plane, in which the model has a positive equilibrium.
- 2. Derive an equation for the Hopf bifurcation of the positive equilibrium of (8.1). Prove that this bifurcation is supercritical, i.e. gives rise to a stable periodic orbit.
- 3. Use **pplane** and **MatCont** to produce representative phase portraits of the model and sketch its simplest possible bifurcation diagram. *Hints*: Fix $l = \frac{1}{2}$ and plot the phase portraits for several different values of m.
- 4. There is a global (heteroclinic) bifurcation in the system. Find numerically m_{HET} for the heteroclinic parameter value when $l = \frac{1}{2}$.

9 Adaptive control - II

Consider the following 3D system

$$\begin{cases} \dot{x} = \mu x + y, \\ \dot{y} = -x + \mu y - xz, \\ \dot{z} = -z + ax^2, \end{cases}$$
(9.1)

where $a \neq 0$. This system appears in the control theory.

- 1. Verify that system (9.1) exhibits a Hopf bifurcation of the equilibrium (x, y, z) = (0, 0, 0) at the parameter value $\mu = 0$.
- 2. Compute the corresponding first Lyapunov coefficient l_1 and predict the direction of the Hopf bifurcation and the stability of the bifurcating limit cycle.
- 3. Verify your predictions by simulations or by numerical continuation of the cycle in MatCont.

10 Hopf bifurcation in the Coimbrator

Consider the following model for changes of atmospheric CO_2 that includes photosynthesis and the carbon cycle:

$$\begin{cases} \dot{x} = \alpha x - xy, \\ \dot{y} = -y - xy + 2\beta z, \\ \dot{z} = \alpha x - \beta z, \end{cases}$$
(10.1)

where α, β are positive parameters.

- 1. Investigate the linear stability of both equilibria.
- 2. Find a Hopf bifurcation curve of one equilibrium, i.e., determine the corresponding $\alpha = \alpha_{\rm H}(\beta)$.
- 3. Compute the first Lyapunov coefficient l_1 .
- 4. Illustrate your findings using simulations in MatCont.